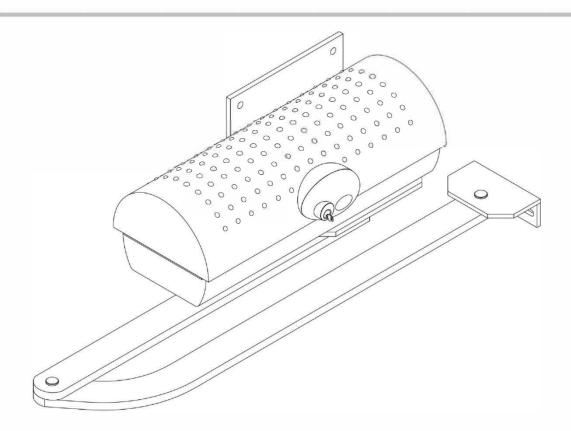
IGEA UL BT

Thalia Control Board





GATE AUTOMATION INSTALLATION SAFETY

While the manufacturer has designed the system under strict safety standards, it is ultimately the installers responsibility to follow and comply with national and local laws, codes and safety standards that apply to the mechanical, electrical and operational aspects of the gate automation system. These include but are not limited to: safety standards established by entities like Underwriters Laboratory (UL), NFPA 70, or codes and laws stated by corresponding state, county or municipality.

While it may not be compulsory, we highly recommend following UL 325 safety standards.

UL 325 VEHICULAR GATE AUTOMATION CLASSIFICATION

This system can be used in Class I, Class II and Class III applications.

- CLASS I RESIDENTIAL VEHICULAR GATE OPERATOR A vehicular gate operator (or system) intended for use in a home of one-to
 four single family dwelling, or a garage or parking area associated therewith.
- CLASS II COMMERCIAL/GENERAL ACCESS VEHICULAR GATE OPERATOR A vehicular gate operator (or system) intended for use
 in a commercial location or building such as a multi-family housing unit (five or more single family units), hotel, garages, retail store, or
 other building servicing the general public.
- CLASS III INDUSTRIAL/LIMITED ACCESS VEHICULAR GATE OPERATOR A vehicular gate operator (or system) intended for use in an industrial location or building such as a factory or loading dock area or other locations not intended to service the general public.
- CLASS IV RESTRICTED ACCESS VEHICULAR GATE OPERATOR A vehicular gate operator (or system) intended for use in a guarded
 industrial location or building such as an airport security area or other restricted access locations not servicing the general public, in which
 unauthorized access is prevented via supervision by security personnel.

UL 325 ENTRAPMENT PROTECTION REQUIREMENTS

For all installation classes, it is required to properly adjust the inherent obstruction sensing system and install warning signs on both sides of the gate, warning pedestrians of the dangers of the automated gate system. For Class I and Class II installations, it is required to add a non-contact device, such as a photoelectric eye **OR** a contact device such as a gate edge. For Class III installations it is required to add a non-contact device, such as a photoelectric eye, **AND** a contact device such as a gate edge **OR** an audio alarm such as a siren, horn or buzzer.

UL325 INSTALLATION RECOMMENDATIONS

- 1. Install the gate operator only when:
 - **a.** The operator is appropriate for the construction and the usage class of the gate.
- **b.** All openings of a horizontal slide gate are guarded or screened from the bottom of the gate to a minimum of 4' (1.2 m) above the ground to prevent a 2-1/4" (6 cm) diameter sphere from passing through the openings anywhere in the gate, and in that portion of the adjacent fence that the gate covers in the open position.
 - c. All exposed pinch points are eliminated or guarded, and guarding is supplied for exposed rollers.
- 2. The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come in contact with the vehicular gate during the entire path of travel of the vehicular gate.
- 3. The gate must be installed in a location so that enough clearance is supplied between the gate and adjacent structures when opening and closing to reduce the risk of entrapment. Swinging gates shall not open into public access areas.
- 4. The gate must be properly installed and work freely in both directions prior to the installation of the gate operator.
- 5. Controls intended for user activation must be located at least six feet (6') away from any moving part of the gate and where the user is prevented from reaching over, under, around or through the gate to operate the controls. Outdoor or easily accessible controls shall have a security feature to prevent unauthorized use.
- **6.** The Stop and/or Reset (if provided separately) must be located in the line-of-sight of the gate. Activation of the reset control shall not cause the operator to start.
- 7. A minimum of two (2) WARNING SIGNS (supplied with the gate operator) shall be installed, one on each side of the gate where easily visible.
- 8. For a gate operator utilizing a non-contact sensor:
 - a. Reference owner's manual regarding placement of non-contact sensor for each type of application.
 - b. Care shall be exercised to reduce the risk of nuisance tripping, such as when a vehicle trips the sensor while the gate is still moving.
- **c.** One or more non-contact sensors shall be located where the risk of entrapment or obstruction exists, such as the perimeter reachable by a moving gate or barrier.
- 9. For a gate operator utilizing a contact sensor such as an edge sensor:
- a. One or more contact sensors shall be located where the risk of entrapment or obstruction exists, such as at the leading edge, trailing edge and post mounted both inside and outside of a vehicular horizontal slide gate.
 - b. One or more contact sensors shall be located at the bottom edge of a vehicular vertical lift gate.
- **c.** A hard wired contact sensor shall be located and its wiring arranged so the communication between the sensor and the gate operator is not subject to mechanical damage.
- **d.** A wireless contact sensor such as the one that transmits radio frequency (RF) signals to the gate operator for entrapment protection functions shall be located where the transmission of the signals are not obstructed or impeded by building structures, natural landscaping or similar obstruction. A wireless contact sensor shall function under the intended end-use conditions.
- **e.** One or more contact sensors shall be located on the inside and outside leading edge of a swing gate. Additionally, if the bottom edge of a swing gate is greater than 6" (152 mm) above the ground at any point in its arc of travel, one or more contact sensors shall be located on the bottom edge.
 - f. One or more contact sensors shall be located at the bottom edge of a vertical barrier (arm).

UL 2018 UPDATE

A WARNING

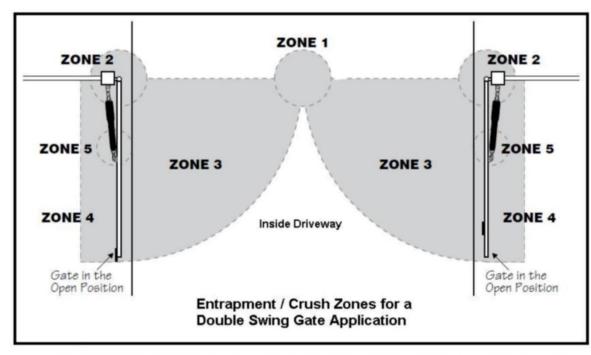
Moving Gate Can Cause Serious Injury or Death

Entrapment / Crush Zones for Double Swing Gate Application

- Zone 1 -Leading edge of the gate and the fence post
- Zone 2 Between the gate and the gate post
- Zone 3 The travel path of the gate
- Zone 4 The space between the gate in the open position and any object such as a wall, fence, tree etc.
- Zone 5 Pinch points between the opener and gate

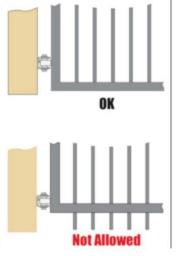
To reduce the risk of INJURY or DEATH:

- . READ AND FOLLOW ALL INSTRUCTIONS
- NEVER let children operate or play with gate controls. Keep the remote control away from children.
- ALWAYS keep people and objects away from the gate. NO ONE SHOULD CROSS THE PATH OF THE MOVING GATE.
- Test the gate operator monthly. The gate MUST reverse on contact with an object or reverse when an object activates the noncontact sensors. After adjusting the force or the limit of travel, retest the gate operator. Failure to adjust and retest the gate operator properly can increase the risk of INJURY or DEATH.
- . Use the emergency release ONLY when the gate is not moving.
- KEEP GATES PROPERLY MAINTAINED. Read the owner's manual.
 Have a qualified service person make repairs to gate hardware.
- The entrance is for vehicles ONLY. Pedestrians MUST use separate entrance.



Base of Swing & Slide Gates

Gates must have smooth bottm edges. No sharp protrusions should exist or exceed 1/2 inch beyond base of gate.



UL325 Entrapment Protection Requirements

- A minimum of two independent* monitored entrapment protection devices are required to be installed at each entrapment zone
- Every installation is unique. It is the responsibility of the installer to install external monitored entrapment protection devices in each entrapment zone
- This vehicular swing gate operator will operate only after installation
 of a minimum of two independent* monitored entrapment protection
 devices in either the open or close direction. If no entrapment zone
 exists in the other direction of gate travel, then the inherent (built into
 the operator) is all that is required in that direction.
- Entrapment protection device types include inherent (built into the operator), monitored external photoelectric sensors or monitored external edge sensors
- This operator is provided with an inherent entrapment protection device built into the operator that serves as one of the two independent devices

^{*} Independent - the same type of device shall NOT be used for both entrapment protection devices.

GENERAL SAFETY

WARNING! An incorrect installation or improper use of the product can cause damage to persons, animals or property.

- Automation should be installed on a gate which is moving freely. Any issue with the smooth opening of closing of a gate will not be corrected by adding automation.
- Scrap packing materials (plastic, cardboard, polystyrene etc) according to the provisions set out by current standards. Keep nylon or polystyrene bags out of children's reach.
- · Keep this instruction manual for future reference.
- This product was exclusively designed and manufactured for the use specified in the present documentation. Any other use not specified in this documentation could damage the product and be dangerous.
- The Company declines all responsibility for any consequences resulting from improper use of the product, or use which is different from that expected and specified in the present documentation.
- · Do not install the product in explosive atmosphere.
- The Company declines all responsibility for any consequences resulting from failure to observe Good Technical Practice when constructing closing structures (door, gates etc.), as well as from any deformation which might occur during use.
- · Follow and comply with national and/or local electrical codes when performing any electrical installation.
- · Disconnect the electrical power supply before carrying out any work on the installation. Also disconnect any buffer batteries, if fitted.
- Fit all the safety devices (photocells, electric edges etc.) which are needed to protect the area from any danger caused by squashing, conveying and shearing, according to and in compliance with the applicable directives and technical standards.
- It is recommended to position at least one luminous signal indication device (blinker) where it can be easily seen for additional safety
- The Company declines all responsibility with respect to the automation safety and correct operation when other manufacturer's components are used.
- Only use original parts for any maintenance or repair operation.
- Do not modify the automation components, unless explicitly authorized In writing by the Company.
- · Instruct the product user about the control systems provided and the manual opening operation in case of emergency.
- · Anything which is not expressly provided for in the present instructions, is not allowed.
- · Installation must be carried out using the safety devices and controls prescribed by the UL 325 Standard.

CHECKING INSTALLATION

Before the automated device is finally put into operation, perform the following checks meticulously:

- · Make sure all components are fastened securely.
- · Check that all safety devices (photocells, pneumatic safety edge, etc.) are working properly.
- · Check the emergency operation control device.
- Check opening and closing operations with the control devices applied.
- · Check the electronic logic for normal (or personalized) operation in the control panel.

ADJUSTING OPERATING FORCE

WARNÍNG: Operating force is adjusted with extreme precision by means of the control unit's electronic control. Operation at the end of travel is adjusted electronically in the control panel. To provide good anti-crush safety, the operating force must be slightly greater than that required to move the leaf both to close and to open it.

CONTROL

There are various options when it comes to the control system (manual, remote control, access control with magnetic badge, etc.) depending on the installation's needs and characteristics. See the relevant instructions for the various control system options. People due to use the automated device must be instructed how to control and use it.

OPERATIONAL SAFETY

The installer is responsible for communicating the following information to the end-user:

This product has been designed and built solely for the purpose indicated herein. Uses not contemplated herein might result in the product being damaged and could be a source of danger.

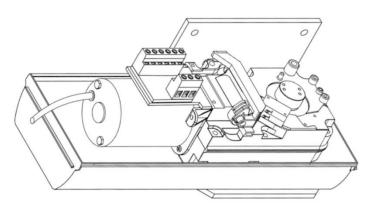
The Firm disclaims all responsibility resulting from improper use or any use other than that for which the product has been designed, as indicated herein, as well as for failure to apply Good Practice in the construction of entry systems (doors, gates, etc.) and for deformation that could occur during use. If installed and used correctly, the automated system will meet the required level of safety. Nonetheless, **it is advisable to observe certain rules of behavior so that accidental problems can be avoided:**

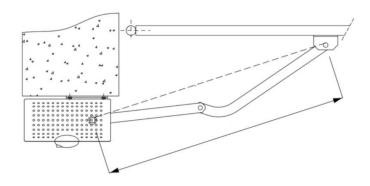
- · Keep adults, children and property out of range of the automated system, especially while it is operating.
- Operate the system when the full path of the gate is within sight.
- It is essential to frequently check that all safety devices are in good working condition.
- This application is not meant for use by people (including children) with impaired mental, physical or sensory capacities, or people who
 do not have suitable knowledge, unless they are supervised or have been instructed by people who are responsible for their safety.
- Children must be supervised to ensure they do not play with the system. Keep remote controls or other control devices out of reach of children in order to avoid the automated system being operated inadvertently.
- Check the system frequently, especially hinges, cables, springs or supports, to detect any loss of balance and signs of wear or damage.
- When cleaning the outside or performing other maintenance work, always cut off mains power.
- Keep the photocells' optics and illuminating indicator devices clean. Check that no branches or shrubs interfere with the safety devices (photocells).
- Do not use the automated system if it is in need of repair. In the event of a malfunction, cut off the power, activate the emergency release to allow access and call in qualified technical personnel (professional installer).
- If the automated system requires work of any kind, employ the services of qualified personnel (professional installer).
- Anything that is not explicitly provided for in these instructions is not allowed.
- The operator's proper operation can only be guaranteed if the information given herein is complied with. The Firm shall not be
 answerable for damage caused by failure to comply with the installation rules and instructions featured herein.
- Have the complete system checked including all safety devices by a qualified professional technician at least once a year.

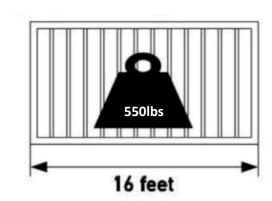
Descriptions and illustrations herein are not binding. While we will not alter the product's essential features, the Firm reserves the right, at any time, to make those changes deemed necessary to improve the product from a technical, design or commercial point of view, and will not be required to update this publication accordingly.



Important. This product is intended to be installed and serviced by a professional technician. The product warranty may be voided if installed or serviced by a unqualified person.



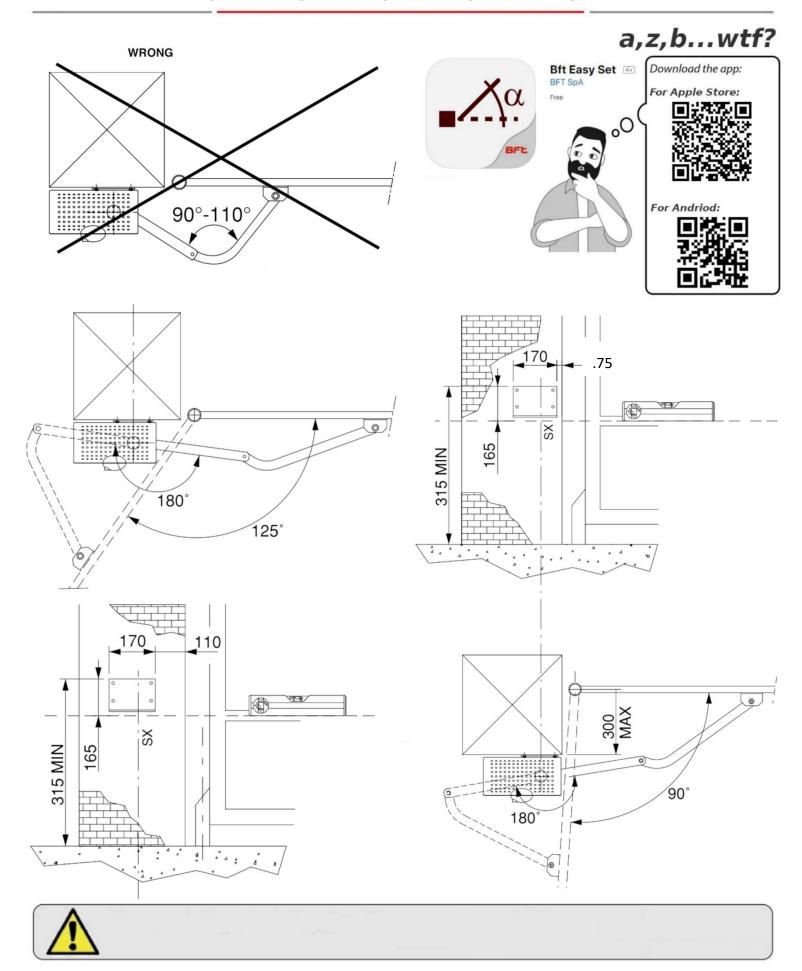


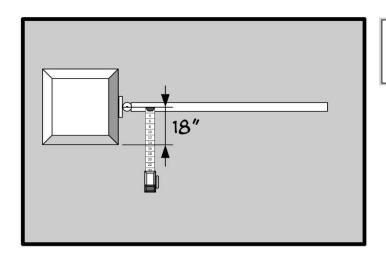


an external locking mechanism is suggested for gates over 10 feet long

WARNING!

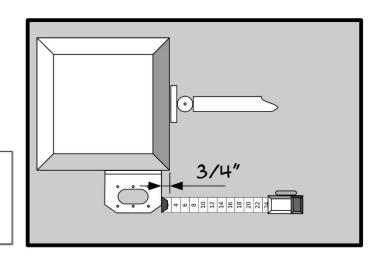
<u>Please read and follow all instructions before installing and operating this product.</u> Follow all local and federal building and electrical codes. BFT is not responsible for faults or damage caused by improper installation, application, or failure to comply with building codes.

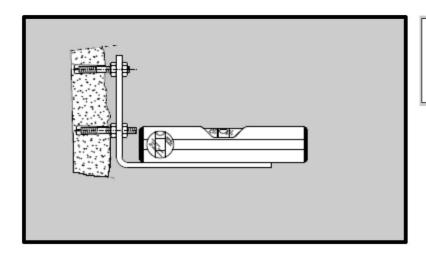




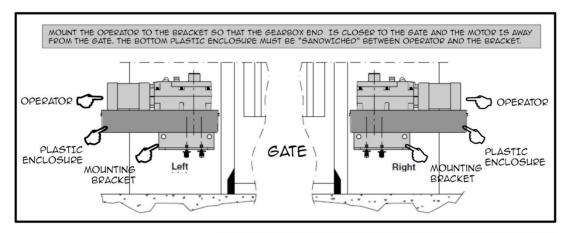
MAXIMUM ALLOWED DISTANCE BETWEEN THE CENTER OF THE HINGE AND THE EDGE OF THE COLUMN IS 18 INCHES

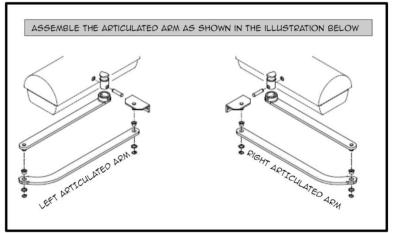
FIX THE IGEA'S MOUNTING BRACKET ¾ OF AN INCH FROM THE INSIDE CORNER OF THE COLUMN USING THE APPROPRIATE ANCHORING HARDWARE FOR THE SURFACE AND/OR COLUMN CONSTRUCTION

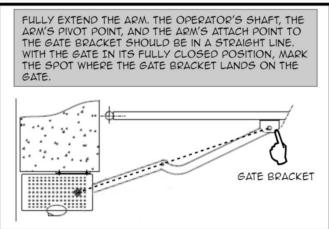


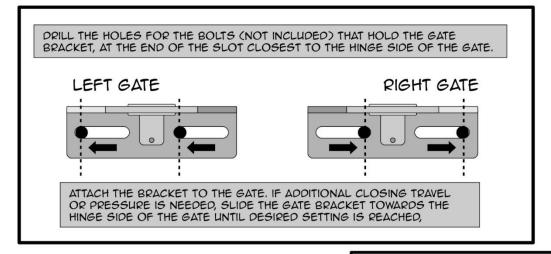


THE MOUNTING BRACKET MUST BE LEVEL. IF INSTALLING TO AN UNEVEN SURFACE, USE THREADED ANCHORS AND NUTS BETWEEN THE BRACKET AND THE SURFACE IN ORDER TO LEVEL IT.







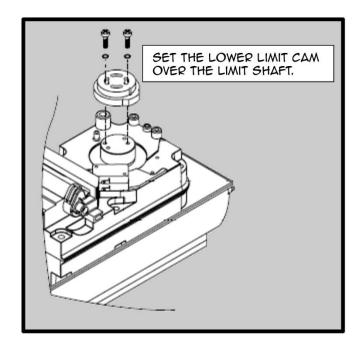


NEXT:

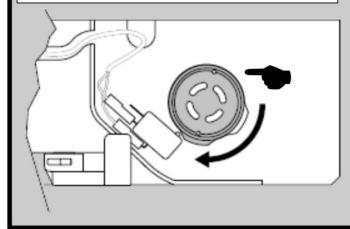
LEFT-SIDE OPERATORS - KEEP IN THE FULLY CLOSED POSITION

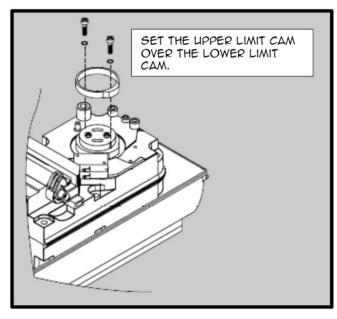
RIGHT-SIDE OPERATORS - MANUALLY

OPEN TO THE DESIRED LIMIT.



TURN THE CAM CLOCKWISE UNTIL IT TRIGGERS THE MICRO-SWITCH AND SECURE TO LOWER LIMIT CAM WITH PROVIDED SCREWS AND FLAT WASHERS





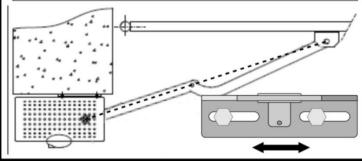
NEXT:

LEFT-SIDE OPERATORS - MANUALLY OPEN THE GATE TO ITS FULLY OPEN POSITION

RIGHT-SIDE OPERATORS -MANUALLY CLOSE THE GATE TO ITS FULLY CLOSED POSITION



ONCE YOU HAVE CONNECTED AND POWERED THE MOTORS TO THE CONTROL BOARD FOLLOWING ITS INSTRUCTIONS, YOU MIGHT NEED TO FINE TUNE THE LIMITS. WHEN THE GATE IS FULLY CLOSED, THE ARM SHOULD BE FULLY EXTENDED. MAKE YOUR FINAL CLOSE LIMIT ADJUSTMENT BY SLIDING THE GATE BRACKET.

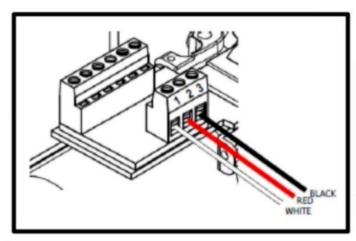


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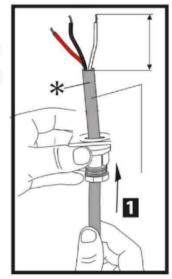
ONLY USE 16 AWG, STRANDED, SUTOW OR SUTOOW CABLE. AVOID SPLICES. IF NECESSARY, A SPLICE MUST BE ABOVE GROUND IN A DRY JUNCTION BOX

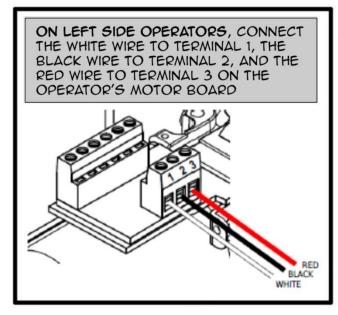
Strip about 1-1/2" off the outer jacket of the motor cable.

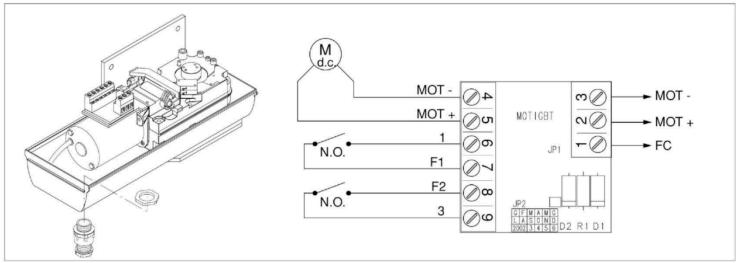
Install the o-ring over the cable so that it is about 1/2" from the edge of the outer jacket



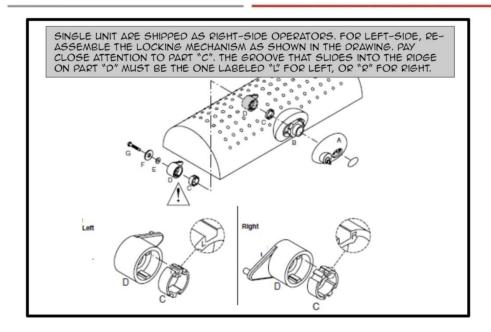
ON RIGHT SIDE OPERATORS, CONNECT THE WHITE WIRE TO TERMINAL 1, THE RED WIRE TO TERMINAL 2, AND THE BLACK WIRE TO TERMINAL 3 ON THE OPERATOR'S MOTOR BOARD

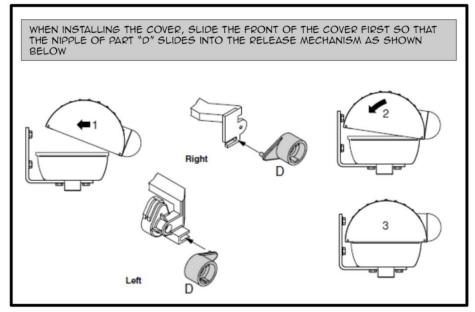


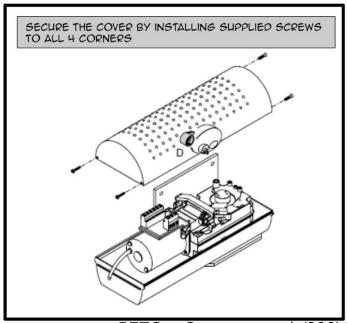




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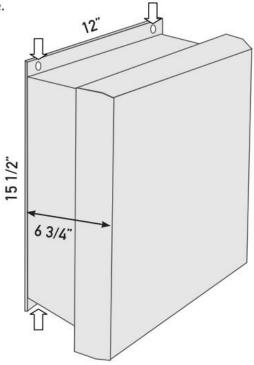




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Mounting the enclosure

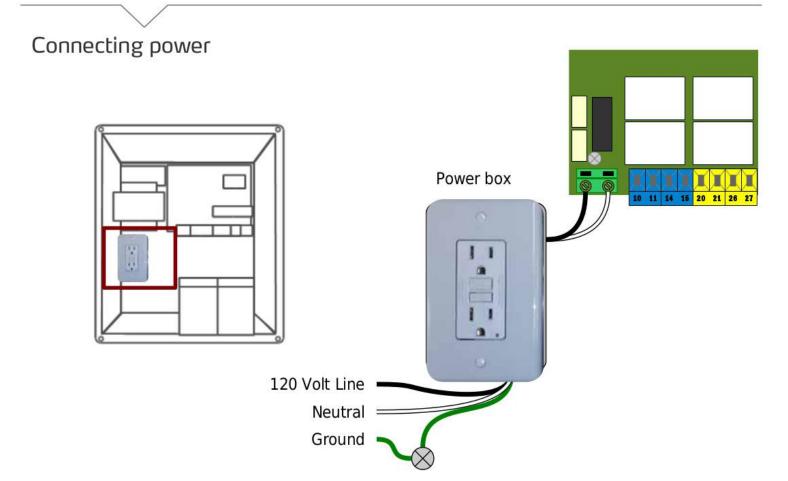
Use the mounting holes on the top and bottom flanges of the enclosure. Do not drill through the interior of the enclosure.

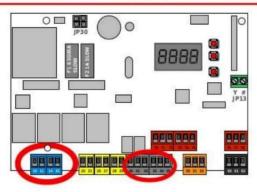


Do not perforate the top of the enclosure



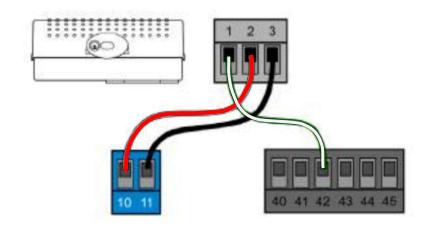
Bring all your wiring and/or conduits through the bottom of the enclosure. For best results, use a step drill bit to perforate the enclosure to the needed size opening





Motor 1

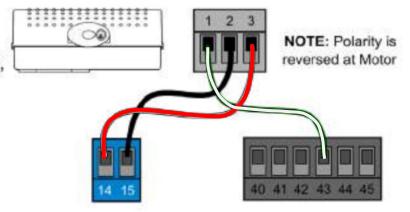
For Single Door Installations, connect your motor wires to Motor 1 motor output (terminals 10 & 11), and Motor 1 Limit input (terminal 42).



Motor 2

For Dual Door Installations,

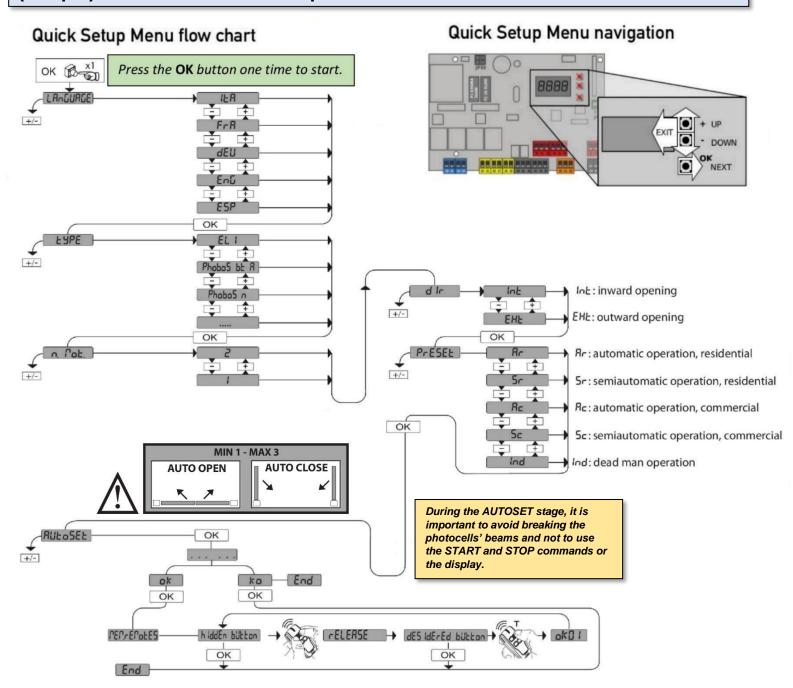
connect your second motor wires to Motor 2 motor output (terminals 14 & 15), and Motor 1 Limit input (terminal 43).



When installing a two leaf gate system, connect the motor wires from the gate that needs to open first to Motor 1 connections (10, 11 & 42), and connect the motor wires from the gate that needs to close first to Motor 2 connections (14, 15, & 43).

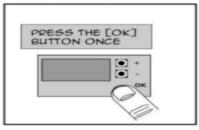
IMPORTANT Photo sensor(s) MUST be properly installed (see p.19-20) BEFORE the AUTOSET procedure!

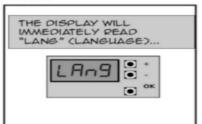
IMPORTANT OPEN and CLOSE limit switches MUST be properly adjusted (see p.9) BEFORE the AUTOSET procedure!



Launch an AUTOSET operation by going to the relevant menu. As soon as you press the OK button, the "......" message is displayed, and the control unit commands the device to perform a full cycle (opening followed by closing), during which the minimum torque value required to move the leaf is set automatically. The number of cycles required for the AUTOSET function can range from 1 to 3. During this stage, it is important to avoid breaking the photocells' beams and not to use the START and STOP commands or the display. Once this operation is complete, the control unit will have automatically set the optimum torque values. Check them and, where necessary, edit them as described in the programming section.

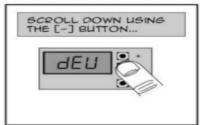
STEP 1. Enter Quick Setup Menu

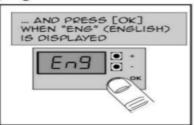


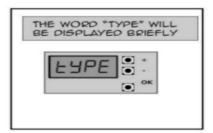




STEP 2. Set the menu language



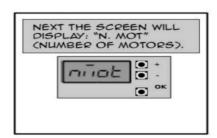




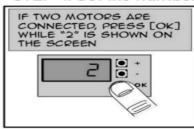
STEP 3. Select the type of operator

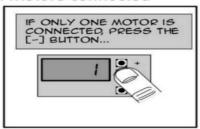


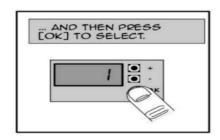




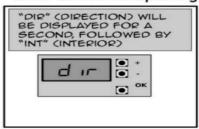
STEP 4. Set the number of motors connected

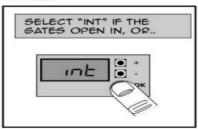


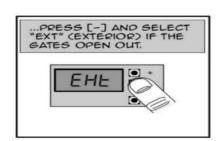




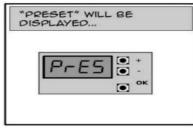
STEP 5. Set the opening direction

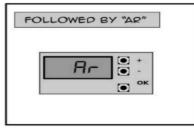






STEP 6. Set the desired preset





USE THE [-] BUTTON TO SCROLL DOWN AND THE [OK] BUTTON TO SELECT YOUR PREFERRED PRESET. PRESETS ARE EXPLAINED ON THE NEXT PAGE.

PRESETS

| FEATURES | AR | SR | AC | sc | IND |
|----------------------------|--------------------------|-------------------------------|-------------------------|---------------------------|------------|
| | AUTOMATIC RESIDENTIAL | SEMI-AUTOMATIC RESIDENTIAL | AUTOMATIC COMMERCIAL | SEMI-AUTOMATIC COMMERCIAL | INDUSTRIAL |
| AUTOMATIC CLOSING TIMER | X | | X | | |
| PRE-ALARM | | | X | X | |
| UNINTERRUPTED OPEN CYCLE | | | X | X | |
| INSTANT REVERSE ON CLOSING | X | | X | | |
| HOLD TO RUN | | | | | X |
| QUICK REMOTE PROGRAMMING | X | X | X | X | |

Automatic Closing Timer: Automatically closes the gate after gate fully opens and all safety devices are cleared.

Pre-Alarm: Energizes auxiliary relay with value set to "6", for 3 seconds before energizing the motors.

Uninterrupted Open Cycle: Remote controls and START input is ignored during the open cycle.

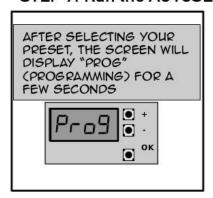
Instant Reverse On Closing: A START command will instantly re-open gates during the close cycle. Otherwise, a START command first stops the gate requiring a second command to re-open.

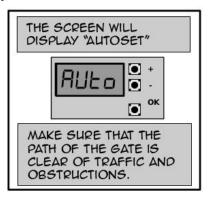
Hold-To-Run: START command is disabled. Gate requires a constant "open " or "close" command for it to run.

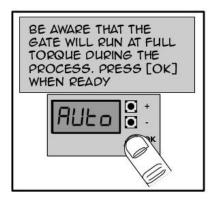
Quick Remote Programming: Allows adding remotes wirelessly using an existing working transmitter.

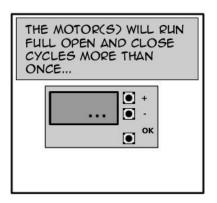
The "Residential" presets are not exclusive for residential applications the same way "Commercial" presets are not exclusive for commercial applications. They can both be used on any application depending on the needs and preferences of such installation. You can further customize your settings by using the Main Programming Menu.

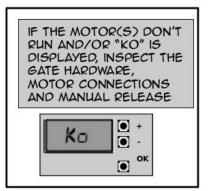
STEP 7. Run the AUTOSET

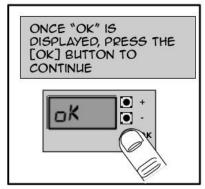




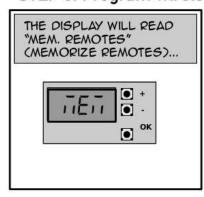


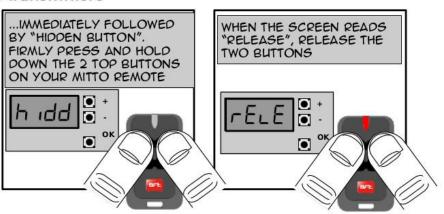


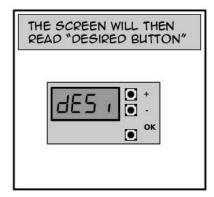




STEP 8. Program wireless transmitters





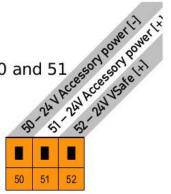




ACCESSORY POWER

24 volts accessories and peripherals can be powered from terminals 50 and 51

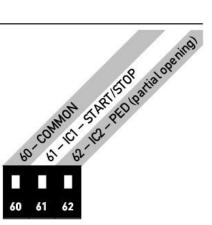
| Terminal | Name | Description |
|----------|-------------|----------------------------------------|
| 50 | - 24 V | Accessory power negative common |
| 51 | + 24 V | Accessory power positive |
| 52 | + 24 V-Safe | Positive power when gate is not closed |



COMMAND INPUTS

The Thalia board provides two command inputs (IC1 and IC2).

| Terminal | Name | Description | Default |
|----------|------|-------------------------|---------|
| 60 | COM | Command positive common | common |
| 61 | IC 1 | Command Input 1 | START |
| 62 | IC 2 | Command Input 2 | PED |

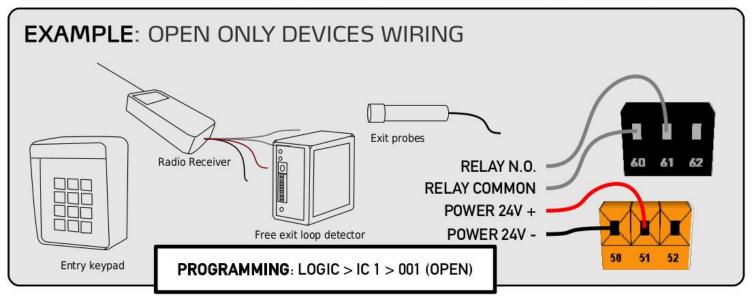


Command inputs 1 and 2 can be re-programmed to perform any of the following functions:

PROGRAMMING: LOGIC > IC # > 000 ~ 006

START Cycles between open, stop and close. Normally used with single push-buttons and radio receivers.
 OPEN Open only command. Used with [open] buttons, free exit and/or open only devices.
 CLOSE Close only. Used with [close] buttons and closing loop detectors
 PED Pedestrian opening. Partially opens Motor 1 only.
 TIMER Hold Open input.
 TIMER PED Holds partially open motor 1

Please refer to LOGIC programming for IC 1 and IC 2 re-programming



NOTE: The same entrapment features are NOT required to be active during both cycles, however, two entrapment features must be present during both cycles.

The Thalia board provides:

- one STOP command input;
- one obstruction sensing device input UL 325-2016 compatible, SAFE 1 with its mandatory supervision circuit input FAULT 1. The system reacts to the input in both opening (stops) and closing (reverses) cycles;

Programmable obstuction sensing device input for SAFE 1, 001 PHOT TEST (default setting) and 005 PHOT CL TEST (reacts to input during closing only)

 two programmable obstruction sensing device inputs, SAFE 2 and SAFE 3, both provided with their optional supervision circuit input FAULT 2 and FAULT 3.

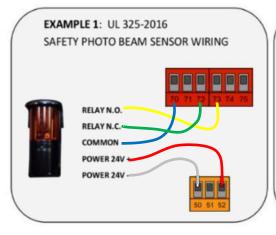
All the 3 safety inputs are **N.C.** (normally closed) contacts. All the FAULT inputs are **N.O.** (normally open) contacts. Below is a table with the terminal numbers and their corresponding functions and default values.

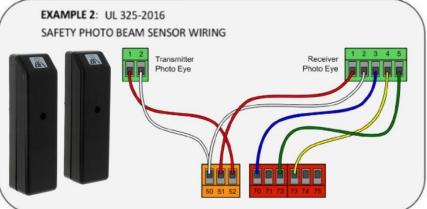
| 70 | 71 | 72 | 73 | 74 | 75 | 76 | 77 | 78 |
|-------------|-----------|-------------------------------------------|--------------------------|-----------------------------------------------------------|--------------|-------------|--------------------------------------------------------------|--------------|
| | | | | | | | | |
| 70 - Common | 71 - STOP | 72 – SAFE 1: PHOT UL 325-16 (obstruction) | 73 -FAULT JUL 325 - 2016 | 74 – SAFE 2 – programmable - default is BAR (safety edge) | 75 - FAULT 2 | 76 - Common | 77 – SAFE 3 – programmable – default is SHADOW (safety loop) | 78 - FAULT 3 |

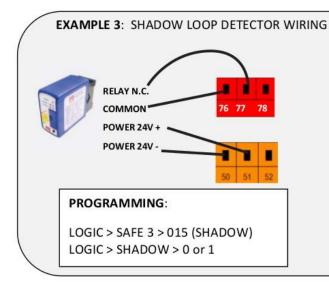
| Terminal | Name | Description | Default | Notes | |
|----------|---------|--------------------------------|--------------|-----------------------------------------------------|--|
| 70 | COM | Safety positive common | Common | | |
| 71 | STOP | Stop command | STOP | Overrides all other commands | |
| 72 | SAFE 1 | Safety input #1 | PHOT | Stops operators during opening, reverses on closing | |
| 73 | FAULT 1 | Supervisory circuit for SAFE 1 | FAULT | Requires opposite relay state from SAFE 1 | |
| 74 | SAFE 2 | Safety input #2 | 006 - BAR | Programmable input (see LOGIC sub-menu) | |
| 75 | FAULT 2 | Supervisory circuit for SAFE 2 | FAULT | LT Requires opposite relay state from SAFE 2 | |
| 76 | COM | Safety positive common | Common | | |
| 77 | SAFE 3 | Safety input #3 | 015 - SHADOW | Programmable input (see LOGIC sub-menu) | |
| 78 | FAULT 3 | Supervisory circuit for SAFE 3 | FAULT | Requires opposite relay state from SAFE 3 | |

Both SAFE 2 and SAFE 3 can be programmed to perform any of the following functions under the LOGIC sub-menu:

| VALUE | FUNCTION | DESCRIPTION |
|-------|--------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 000 | PHOT | System reacts to the input in both opening (stops) and closing (reverses) cycles |
| 001 | PHOT TEST | Same as above. Requires the device to be supervised (FAULT active) |
| 002 | PHOT OP | System reacts to the input only during the opening cycle (stops) |
| 003 | PHOT OP TEST | Same as above. Requires the device to be supervised (FAULT active) |
| 004 | PHOT CL | System reacts to the input only during the closing cycle (reverses) |
| 005 | PHOT CL TEST | Same as above. Requires the device to be supervised (FAULT active) |
| 006 | BAR | Safety edge input. It reacts in both opening and closing. It stops and partially reverses |
| 007 | BAR TEST | Same as above. Requires the device to be supervised (FAULT active). |
| 800 | BAR 8K2 | Safety edge input with EOL resistor as supervision method. Active only on SAFE 2 |
| 009 | BAR OP | Safety edge input. During opening it stops and partially reverses. During closing it stops. |
| 010 | BAR OP TEST | Same as above. Requires the device to be supervised (FAULT active) |
| 011 | BAR OP 8K2 | Safety edge input with EOL resistor as supervision method. During opening it stops and partially reverses. During closing it stops. Active only on SAFE 2 |
| 012 | BAR CL | Safety edge input. During closing it stops and partially reverses. During opening it stops. |
| 013 | BAR CL TEST Same as above. Requires the device to be supervised (FAULT active) | |
| 014 | Safety edge input with EOL resistor as supervision method. During closing it stops and partially rev During closing it stops. Active only on SAFE 2 | |
| 015 | SHADOW | Safety loop input. If the contact is closed, it prevents any movement of the leafs when gate is open (VALUE 0 of the LOGIC SHADOW) or when the gate is both open and closed (VALUE 1 of the LOGIC SHADOW). See chart example N. 3 on next page |





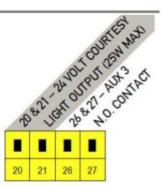


| GATE POSITION | LOGIC "SHADOW" | LOOP CONTACT | OPERATION |
|------------------|-------------------|-----------------|---------------------|
| CLOSED | 0 | CLOSED | Opening allowed |
| CLOSED | 0 | OPEN | Opening allowed |
| IN MOVEMENT | 0 | CLOSED | No effect |
| IN MOVEMENT | 0 | OPEN | No effect |
| OPEN | 0 | CLOSED | Closing allowed |
| OPEN | 0 | OPEN | Closing not allowed |
| CLOSED | 1 | CLOSED | Opening allowed |
| CLOSED | 1 | OPEN | Opening not allowed |
| IN MOVEMENT | 1 | CLOSED | No effect |
| IN MOVEMENT | 1 | OPEN | No effect |
| OPEN | 1 | CLOSED | Closing allowed |
| OPEN | 1 | OPEN | Closing not allowed |

AUXILIARY OUTPUTS

The Thalia board has two auxiliary outputs. The first (20 & 21), is a 24 volt, courtesy light output that will activate upon activation of the gate, and will remain on for 90 seconds after the gate has closed.

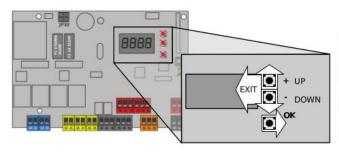
The second output labeled **AUX 3** (26 & 27), is defaulted as second channel radio receiver output, but can be reprogrammed to perform any of the following functions under the **LOGIC** sub-menu:



AUX3 max contact rating: 24v, 3W (transistor output)

| VALUE | FUNCTION |
|-------|--------------------------------------------------------------------------------------------------|
| 0 | 2ND CHANNEL RECEIVER OUTPUT. Output active when transmitter activates the 2nd channel |
| 1 | GATE OPEN LIGHT. Output active when gate is not closed. flashes while closing |
| 2 | COURTESY LIGHT. Output active during and for 90 seconds after operation. |
| 3 | GATE NOT CLOSED. Output active until close limit is reached |
| 4 | START OF CYCLE. Output active for 1 second at the beginning of each cycle |
| 5 | GATE OPEN ALARM. Output active if gate is held open for more than double the timer to close time |
| 6 | GATE RUNNING. Output active while motors are powered |
| 7 | SOLENOID LOCK. Output active for 2 second at the beginning of open cycle |
| 8 | MAGNETIC LOCK. Output active when gate is closed |
| | |

Main Programming Menu navigation



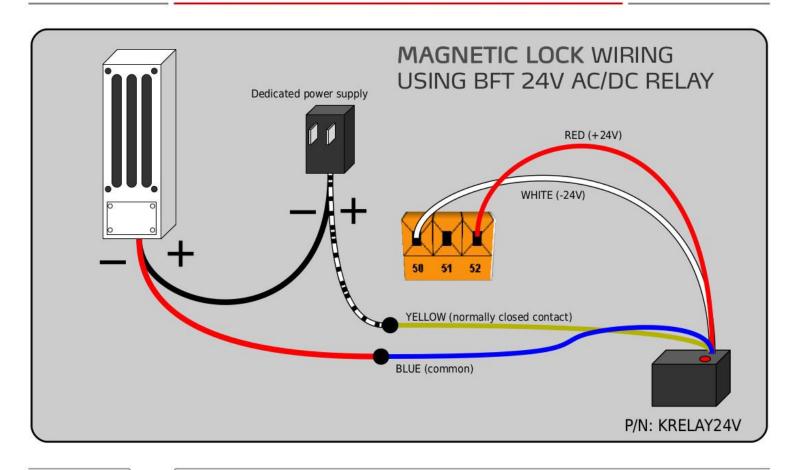
Pressing the [+] button scrolls **up** or **increases** value

Pressing the [-] button scrolls **down** or decreases value

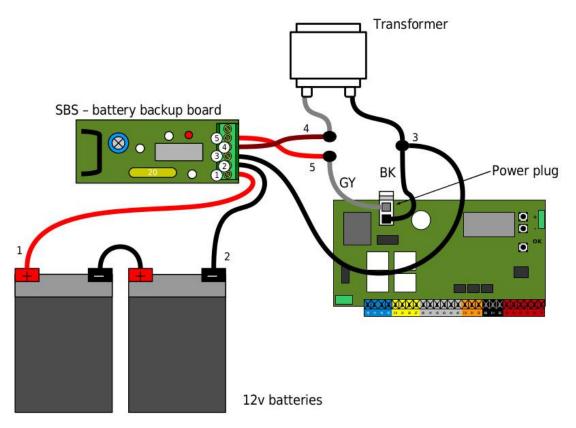
Pressing the [OK] button serves as **ENTER**Pressing [+] and [-] at the same time serves as **BACK**

| (Parameters) PARAM | Sub-menu. All numerical value are set in this area (times, forces, & speeds). |
|--------------------|---------------------------------------------------------------------------------|
| LOGIC | Sub-menu. All features and functions are selected in this area . |
| RADIO | Sub-menu. Built-in receiver programming (remote controls and wireless devices). |
| DEFAULT | Restores all factory settings. Has no effect on RADIO programming. |
| LANGUAGE | Selection of menu language. |
| AUT0SET | Motor learn feature. |
| STAT | Provides firmware and memory information. |
| PASSWORD | Password setting for wireless programmer. |

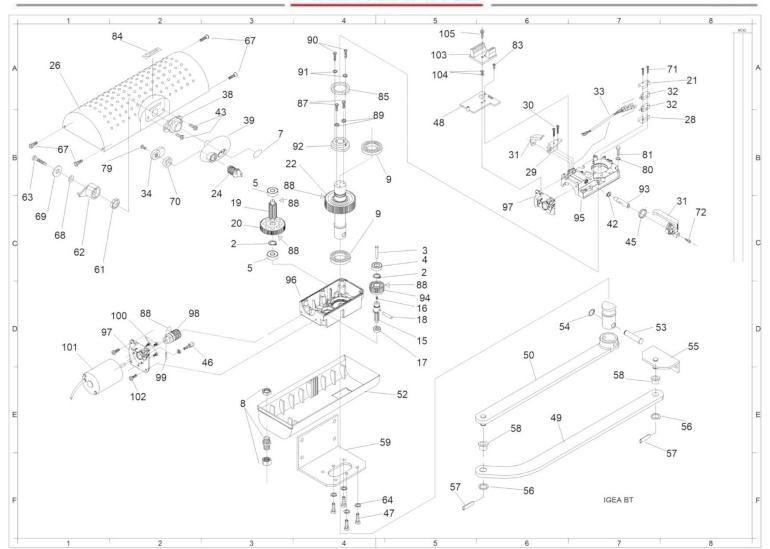
| MAIN | SELECTION | DESCRIPTION | DEFAULT | RANGE |
|-------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|-------|
| | OPEN DELAY TIME | Motor 2 opening delay in seconds | | 0-10 |
| | CLS DELAY TIME | Motor 1 closing delay in seconds | | 0-10 |
| | TCA | Auto-close time adjustment in seconds | | 1-180 |
| | TRF. LGHT.CLR. T | Traffic zone clear time adjustment in seconds | | 1-180 |
| | OP. DIST. SLOWD | Slowdown starting distance from end of open travel expressed in percentage | | 0-50 |
| PARAM > | CL. DIST. SLOWD | Slowdown starting distance from end of close travel expressed in percentage | | 0-50 |
| | DIST. DECEL | Slowdown starting distance from end of open and close travel expressed in percentage | | 0-50 |
| | OP. FORCE | Percentage of opening force exerted over the AUTOSET value before obstruction is sensed | | 1-99 |
| | CLS. FORCE | Percentage of closing force exerted over the AUTOSET value before obstruction is sensed | | 1-99 |
| | OP SPEED | Motor opening speed expressed in percentage | | 15-99 |
| | CLSPEED | Motor closing speed expressed in percentage | | 15-99 |
| | SLOW SPEED | Slowdown speed expressed in percentage from maximum speed. | 25 | 15-99 |
| LOGIC > | MOTOR TYPE | 1=Eli 250; 2=Phobos BT, 3=Igea BT | 0 | 0-3 |
| 77 71 | TCA | Timer to Close Automatically. O=OFF / 1=ON | 0 | 0-1 |
| | FAS T CLS. | Closes when sensors are cleared. O=OFF / 1=ON | 0 | 0-1 |
| | STEP-BY-STEP MOVEMENT * | Determines how the system reacts when a START command is received during operation | 0 | 0-2 |
| | SHADOW | Configuration of safety loop input terminal 74 or 77 when SAFE 2 or SAFE 3 are set as 015 (SHADOW). Prevent any movement of the leafs when gate is open (VALUE 0) or when the gate is both open and closed (VALUE 1). | 0 | 0-1 |
| | SAFE 3* | Configuration of safety input terminal 76. Defaulted as SHADOW (Safety loop) | 15 | 0-15 |
| | PRE-ALARM | Gate running output (AUX value=6) closes 3 sec. before gate movement. O=OFF / 1=ON | 0 | 0-1 |
| | HOLD-TO-RUN | Requires continuous OPEN or CLOSE command input for gate to operate. O=OFF / 1=ON | 0 | 0-2 |
| | IBL OPEN | Ignores START input during the opening cycle. O=OFF / 1=ON | 0 | 0-1 |
| | IBL TCA | Ignores the START input while counting down for automatic closing. O=OFF / 1=ON | 0 | 0-1 |
| | IBL CLOSE | Ignores the START input during the closing cycle. O=OFF / 1=ON | 0 | 0-1 |
| | RAM BLOW C. OP | Pushes gate against physical stop before opening | 0 | 0-1 |
| | RAM BLOW C. CL | Pushes gate against physical stop before closing | 0 | 0-1 |
| | BLOC PERSIST | Hourly push against physical stop | 0 | 0-1 |
| | PRESS SWC | Pushes gate against physical stop for .5 seconds after close limit has been reached. | 0 | 0-1 |
| | ICE | Continuous force learning on every operation. | 0 | 0-1 |
| | 1 MOT. ON | Single Motor operation. O= (2)motors; 1=(1)motor. | 0 | 0-1 |
| | OPEN IN OTHER DIRECT. | O = Pull to open; 1 = Push to open | 0 | 0-1 |
| (| SAFE1* | Configuration of safety input terminal 72. Defaulted as Phot Test (Obstruction). | 1 | 185 |
| e page 20 { | SAFE 2 * | Configuration of safety input terminal 74. Defaulted as BAR (Safety Edge) | 6 | 0-15 |
| l | SAFE 3 * | Configuration of safety input terminal 76. Defaulted as SHADOW (Safety loop) | 15 | 0-15 |
| ſ | IC 1 * | Configuration of command input terminal 61. Defaulted as Start E | 0 | 0-6 |
| e page 19 | IC 2 * | Configuration of command input terminal 62. Defaulted as Ped (Partial open) | 4 | 0-6 |
| e page 21 | AUX 3 * | Configuration of auxiliary output terminals 26 & 27. Defaulted as 2 nd channel contacts. | 0 | 0-8 |
| | FIXED CODE | Rolling code defeat. O = rolling code; 1 = fixed code | 0 | 0-1 |
| | RADIO PROG | Quick remote programming, O = disabled; 1 = enabled | 1 | 0-1 |
| | SERIAL MODE | 0 = Slave unit; 1 = Master unit: | 0 | 0-1 |
| | ADDRESS | Unit's network identification number. | 0 | 0-127 |
| | EXPI1* | Configuration of Expansion board input 1. Defaulted as Start command. | 1 | 0-14 |
| | EXPI 2 * | Configuration of Expansion board input 2. Defaulted as Start command. | 0 | 0-10 |
| | EXPO1* | Configuration of Expansion board output 1. Defaulted as Traffic light control | 9 | 0-9 |
| | EXPO 2 * | Configuration of Expansion board output 2. Defaulted as Traffic light control | 9 | 0-9 |
| | TRAFFIC LIGHT PREFLASHING | Red light flashes for 3 sec. at every start. 0 = Off; 1 = On | 0 | 0-1 |
| | TRAFFIC LIGHT RED LAMP ALWAYS ON | Red light remains on when gate is closed. O = Off; 1 = On | 0 | 0-1 |
| | ADD START | Learns transmitter button as START command | | |
| RADIO > | ADD 2CH | Learns transmitter button as 2 nd channel | | |
| | ERASE 64 | Erase complete memory | | |
| | COD RX | Show receiver ID Code | | |
| | WK | W LINK. | | |
| DEFAULT | Restores board to factory s ettings. N | | | |
| | ITA | Italian | | |
| | FRA | French | | |
| ANGUACE - | DEU | German | | |
| ANGUAGE > | ENG | English | | |
| | ESP | Spanish | | |
| AUTOSET | Maria de Mar | utomatically adjust its FORCE settings | | |
| L. SW ADJ | Limit of travel adjus tment. Only available | | | |
| STAT > | VERS | 500 00 00 00 00 00 00 00 00 00 00 00 00 | | |
| 21/11/2 | N. CYCLES | Displays board firmware version. Displays number of hundreds of cycles (001=100; 010=1000; 100=10,000) | | |
| | | | | |
| | N. REMOTES | Displays the number of remotes in memory. | | |
| | ERR | Displays the last 30 board errors in descending order. | | |



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IGEA BT SWING GATE MOTOR 24V – P935070 00002
IGEA PLASTIC COVERS – I098121
IGEA LIMIT/MOTOR BOARD KIT – I098129
PRIMARY ARM/LEVER PAINTED – I100107 10001
SECONDARY ARM/LEVER PAINTED – I100106 10001
GATE BRACKET KIT – I300041 10001
KIT KNOB IGEA BT GRAY – I200012 10001
KIT CAM LIMIT SWITCH IGEA – I300040 10001

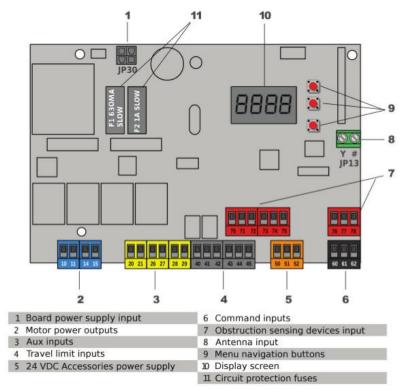
MAINTENANCE

Disconnect the power supply when carrying out any maintenance operations.

- Lubricate the IGEA-BTs of the maneuvering arm regularly.
- Clean the lenses of the photocells every so often.
- In the event of any anomalous functioning which cannot be resolved, disconnect the power supply and contact a specialized technician (installer). Whilst the automation is out of order, activate the manual release to allow manual opening and closing 0

COMMON ERROR CODES

| ERROR | DESCRIPTION | ERROR | DESCRIPTION |
|-------|----------------------------------------------------|-------|----------------------------------------------------|
| ER20 | MOTOR 2 IMPROPER ENCODER MOVEMENT DETECTED | ER35 | MOTOR 1 OBSTACLE DETECTION DURING OPENING |
| ER22 | MOTOR 2 OPPOSITE MOVEMENT | ER36 | MOTOR 1 OBSTACLE DETECTION DURING CLOSING |
| ER25 | MOTOR 1 IMPROPER ENCODER MOVEMENT DETECTED | ER37 | MOTOR 1 OBSTACLE DETECTION DURING OPENING SLOWDOWN |
| ER27 | MOTOR 1 OPPOSITE MOVEMENT | ER38 | MOTOR 1 OBSTACLE DETECTION DURING CLOSING SLOWDOWN |
| ER30 | MOTOR 2 OBSTACLE DETECTION DURING OPENING | ER40 | THERMAL OVERLOAD |
| ER31 | MOTOR 2 OBSTACLE DETECTION DURING CLOSING | ER61 | OPERATING ON BATTERY POWER |
| ER32 | MOTOR 2 OBSTACLE DETECTION DURING OPENING SLOWDOWN | ERSW | ERROR SETTING LIMITS |
| ER33 | MOTOR 2 OBSTACLE DETECTION DURING CLOSING SLOWDOWN | ERF9 | LOCK OUTPUT OVERLOAD |
| ERF3 | SAFETY INPUT CONFIGURATION ERROR | ER01 | PHOTOCELL TEST FAILED |



D111881 00001 Thalia Board Replacement

OPTIONS AND ACCESSORIES



Thalia UL SE Small enclosure no battery back-up



UL Alarm and Reset Included in small and large enclosure

Key Pad

AT&T or T-Mobile.



THALIA UL LE-B

P/N: KTHALIA12U Large 12" x 14" control board enclosure. Includes battery backup with (2) 12V, 9 Ah batteries. 115 volt outlets for accessories.



Q.Bo Touch

P/N: P121024

10 channel wireless keypad. With memory for up to 99 codes, a single keypad can control up to 10 devices in a single location.



information on models available.

CLONIX 2E

BFT offers a full range of cellular and WiFi systems from text

only to multi family systems. Please contact BFT for more

BFT Cell Box Plus -Cellular Access System with

Provide entry to properties using cellular technology. Cost savings

line needed. The system will call four numbers sequentially. 1000

user back lit keypad with hold open feature through keypad or APP

which is free from Itunes or Google play. System is compatible with

on installation with elimination of phone lines from the home no land

P/N: D113674 00001

Two channel external, weatherproof

receiver.

With memory for 128 or 2048 transmitters (optional), it is capable of controlling two independent gates or doors. Programmable relays can also be used as "hold open" feature"



AEL 433

P/N: D113632 External antenna tuned for 433Mhz, doubles the standard range of the remote controls.



MITTO

P/N: D111904 (2 buttons)
P/N: D111906 (4 buttons) Extended
range (200 ft. under optimal
conditions) two button remote
control. Can be used to operate two
separate gates or, combined with the
Clonix 2E, as ___ nd hold open
control. Also available with four
buttons.



POLARIZED IR SENSOR

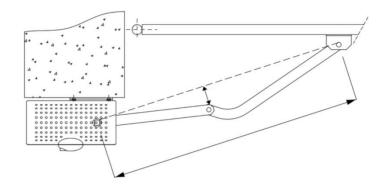
P/N: KIRPOLAPHOT001
30 ft. range. The polarized lens improves performance of the sensor under rainy, foggy or damp conditions. 2 axis adjustment for ease of installation. Includes reflector hood. 12 ~250 v ac/dc



Q.Bo Key

P/N: P121017 NEED Vandal resistant key switch. Can send two individual commands (contact closures) or operate two separate gates or doors.

AT A GLANCE QUICK REFERENCE



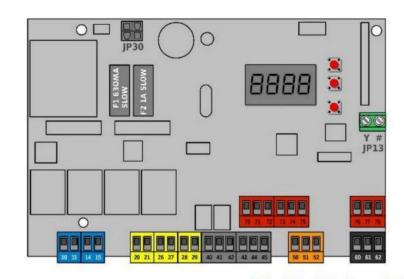
Programming

Quick Setup Menu: Press OK once



Main Programming Menu: Press **OK** twice <u>RAPIDLY</u>

| (Parameters) PARAM | Sub-menu. All numerical value are set in this area (times, forces, & speeds). |
|--------------------|---------------------------------------------------------------------------------|
| LOGIC | Sub-menu. All features and functions are selected in this area. |
| RADIO | Sub-menu. Built-in receiver programming (remote controls and wireless devices). |
| DEFAULT | Restores all factory settings. Has no effect on RADIO programming. |
| LANGUAGE | Selection of menu language. |
| AUTOSET | Motor learn feature. |
| STAT | Provides firmware and memory information. |
| PASSWORD | Password setting for wireless programmer. |





10 & 11 Motor 1 power output. Polarity reverses during close cycle 14 & 15 Motor 2 power output. Polarity reverses during close cycle 20 & 21 Dry contact for external lock. N.O. / N.C. selectable 26 & 27 Auxiliary dry contact, Programmable, Recy'r 2nd channel default 28 & 29 UL alarm contact. N.O. Closes on double obstruction condition 40 - 45 Limit swithes inputs. 50 & 51 Accessory power 24VDC 50 & 52 Switched accessory power 24VDC. Turns off when gate closes. 60 & 61 Input 1. Defaulted as OPEN command. 60 & 62 Input 2. Defaulted as CLOSE command. 70 & 71 STOP / RESET command input. N.C. 70 & 72 SAFE 1. Obstruction sensor input. Defaulted as Photo TEST Obstruction (Loop and/or Photo) 70 & 73 Circuit supervision for SAFE 1 70 & 74 SAFE 2. Obstruction sensor input. Defaulted as CONTACT (Safety edge) obstruction sensing 70 & 75 Circuit supervision for SAFE 2 76 & 77 SAFE 3. Obstruction sensor input. Defaulted as SHADOW sensor input 76 & 78 Circuit supervision for SAFE 3