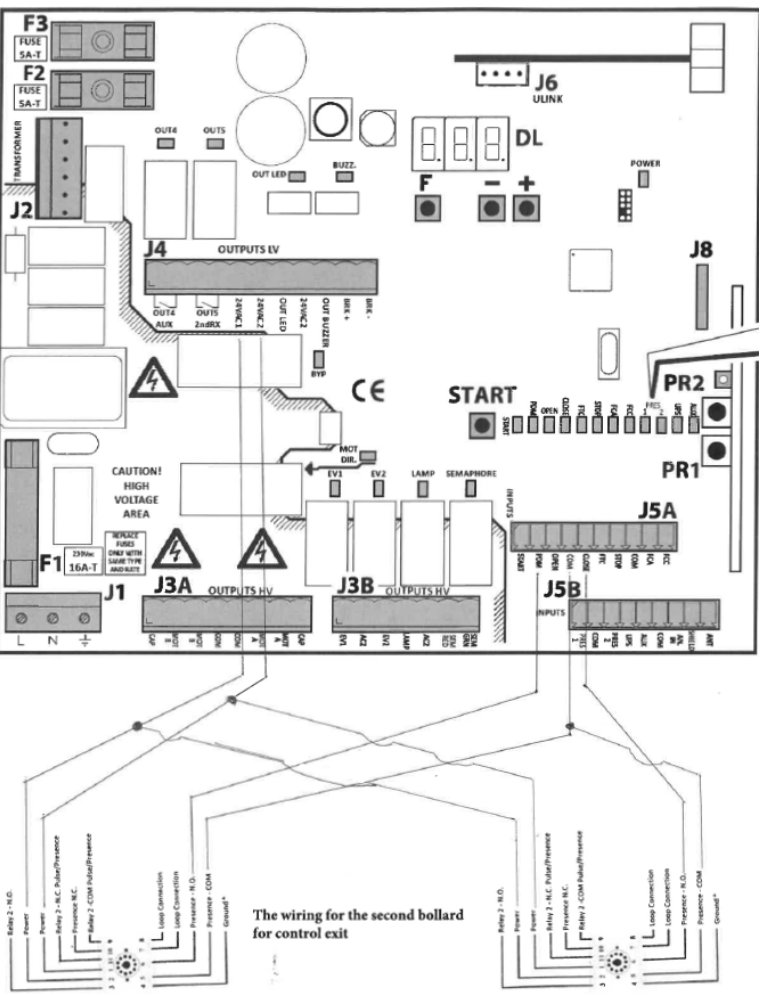
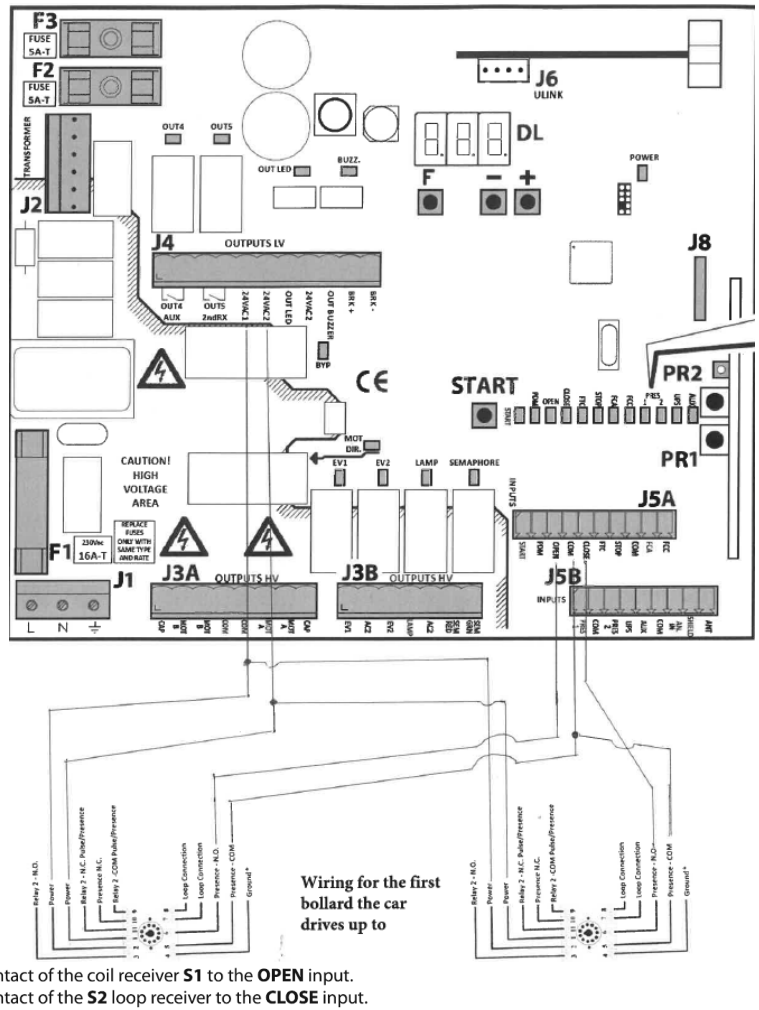


For added security you can connect 2 wires to Out 4 (programmable relay) from the first control board and connect it to the stop and comm from the second control board and program it to option: 04 this way if the first bollard is in the up position the second bollard will go down but if the first bollard is in the down position the second bollard won't go down until the first one is in the up position

For added security you can connect 2 wires to Out 4 (programmable relay) from the second control board and connect it to the stop and comm from the first control board and program it to option: 04 this way if the second bollard is in the up position the first bollard will go down but if the second bollard is in the down position the first bollard won't go down until the second one is in the up position



- Connect the **N.O.** contact of the coil receiver **S1** to the **OPEN** input.
- Connect the **N.O.** contact of the **S2** loop receiver to the **CLOSE** input.
- The dimensional values given are only approximate.

- Connect the **N.O.** contact of the **S1** loop receiver to **PDM** input.
- Connect the **N.O.** contact of the **S2** loop receiver to **CLOSE** input.
- The dimensional values given are approximate.

	PARAMETER	DATA	DESCRIPTION
Pr=02	CL	02	The close command acts as a close-when-release and safety function.
	r1	02	Radio channel 1: Open
	FP	01	Opening consent
	LO	01	Semiautomatic logic
	CP	00	Commands during pause is OFF

	PARAMETER	DATA	DESCRIPTION
Pr=03	CL	02	The close command acts as a close-when-released and safety function.
	r1	00	Radio channel 1: Disabled
	FP	01	Opening consent
	LO	01	Semiautomatic logic
	CP	00	Command during pause is OFF